

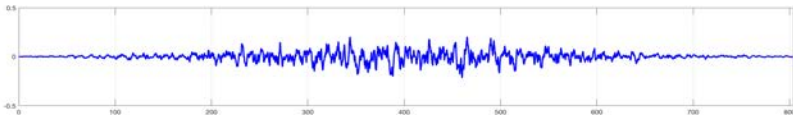


The Alber equation: Landau damping & rogue waves in the ocean

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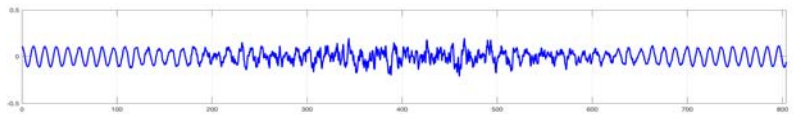


WAVES, PROBABILITIES AND MEMORIES
NTUA, 4-5 July 2022

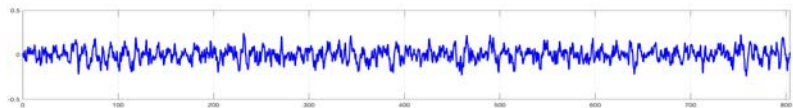


NLS + decay at infinity

“always stable”



NLS + plane wave solution + localized perturbation
“modulation instability”



NLS + “homogeneous” background solution + localized perturbation
both stability & instability are possible

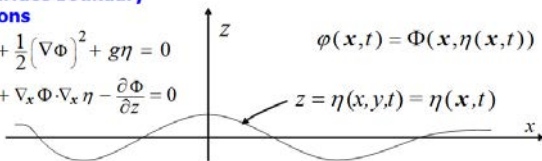
Classical ideal hydrodynamics – the Cauchy problem

- Assume **perfect knowledge of all initial fields**
- Assume bounded domain or **very simple behaviour at infinity**
- Recover **everything** at later times

Free-surface boundary conditions

$$\frac{\partial \Phi}{\partial t} + \frac{1}{2}(\nabla \Phi)^2 + g\eta = 0$$

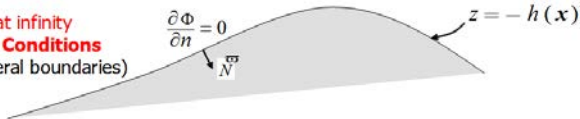
$$\frac{\partial \eta}{\partial t} + \nabla_x \Phi \cdot \nabla_x \eta - \frac{\partial \Phi}{\partial z} = 0$$



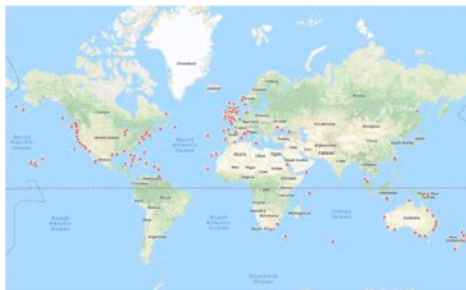
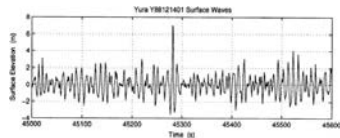
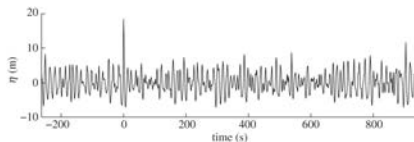
$$\Delta \Phi = 0, \quad \text{in } D_h^\eta(X)$$

$$D_h^\eta(X) = \left\{ (x, z) \in \mathbb{R}^2 \times \mathbb{R} : x \in X, -h(x) < z < \eta(x, t) \right\}$$

conditions at infinity
(or **lateral Conditions**
in finite lateral boundaries)



What can the Cauchy problem say, e.g., about Rogue Waves?



Map from [E. Didenkulova, *Ocean & Coastal Management* 2020]

Find initial conditions that reproduce them (?)

Random inhomogeneous fields of nonlinear water waves

Background:

- I. E. Alber, **Proceedings of the Royal Society A** (1978)
~ 240 citations in [Google scholar](#)
- D. R. Crawford, P. G. Saffman, H. C. Yuen, **Wave motion** (1980)
~ 150 citations in [Google scholar](#)

This talk is based on:

- A. Athanassoulis, G. Athanassoulis and T. Sapsis,
Journal of Ocean Engineering and Marine Energy (2017)
- A. Athanassoulis, **OMAE 2018**
- A. Athanassoulis, G. Athanassoulis, M. Ptashnyk and T. Sapsis,
Kinetic and Related Models (2020)
- A. Athanassoulis and O. Gramstad, **Fluids** (2021)

Ocean waves modelling

- Gravity waves can be approximated by an **envelope** equation,

$$\eta(x, t) = \text{Re} \left[u(x, t) e^{i(k_0 \cdot x - \omega_0 \cdot t)} \right], \quad \omega_0 = \sqrt{gk_0},$$

which turns out to be of **NLS** type

$$i\partial_t u + \underbrace{\frac{\sqrt{g}}{8k_0^{3/2}}}_{p/2} \Delta u + \underbrace{\frac{\sqrt{g}}{2} k_0^2}_{q/2} |u|^2 u = 0, \quad k_0 \sim (0.01, 2).$$

The order parameter is **slope**, $\beta \sim \frac{H_s k_0}{8\pi} < 0.1$.

- Sea states** are typically **stationary & homogeneous** in mesoscales, characterised primarily through their **autocorrelation / spectrum**,

$$E \left[u(x, t) \bar{u}(x', t) \right] = \Gamma(x - x') + o(1),$$

$$\mathcal{F}_{y \rightarrow k}[\Gamma(y)] = P(k)$$

2nd moments + Gaussian closure + Quasi-homogeneity

$$i\partial_t \mathbf{u} + \frac{p}{2} \Delta \mathbf{u} + \frac{q}{2} |\mathbf{u}|^2 \mathbf{u} = \mathbf{0}$$

$$R(\alpha, \beta, t) = E[u(\alpha, t) \bar{u}(\beta, t)]$$



$$i\partial_t \mathbf{R} + \frac{p}{2} (\Delta_\alpha - \Delta_\beta) \mathbf{R} + \frac{q}{2} E[u(\alpha, t) \bar{u}(\beta, t) [u(\alpha, t) \bar{u}(\alpha, t) - u(\beta, t) \bar{u}(\beta, t)]] = \mathbf{0}$$



gaussian closure : Complex Isserlis Theorem,

$$E[u(\alpha, t) \bar{u}(\alpha, t) u(\alpha, t) \bar{u}(\beta, t)] = 2E[u(\alpha, t) \bar{u}(\beta, t)] E[u(\alpha, t) \bar{u}(\alpha, t)]$$



quasi-homogeneity : $R(\alpha, \beta, t) = \Gamma(\alpha - \beta) + \varepsilon \rho(\alpha, \beta, t)$



$$i\partial_t \rho + \frac{p}{2} (\Delta_\alpha - \Delta_\beta) \rho + q [\Gamma(\alpha - \beta) + \varepsilon \rho(\alpha, \beta)] [\rho(\alpha, \alpha) - \rho(\beta, \beta)] = \mathbf{0}.$$

[I. E. Alber, PRSA 1978]

The Alber-Fourier equation (AF)

f is the inhomogeneity, in an appropriate frame of reference. The spectrum P describes the homogeneous background.

$$\begin{aligned}
 & \underbrace{\partial_t f - 4\pi^2 i p k \cdot X f}_{\text{free-space}} + \underbrace{q i \left[P(k - \frac{X}{2}) - P(k + \frac{X}{2}) \right]}_{\text{interaction with spectrum}} \check{n}(X, t) + \\
 & + \underbrace{\varepsilon q i \int_s \check{n}(s, t) \left[f(X - s, k - \frac{s}{2}) - f(X - s, k + \frac{s}{2}) \right]}_{\text{self-interaction of inhomogeneity}} ds = 0. \\
 & \underbrace{\check{n}(X, t) = \int_{\xi} f(X, \xi, t) d\xi}_{\text{position density}}, \quad \underbrace{f(X, k, 0) = f_0(X, k)}_{\text{initial data}}.
 \end{aligned}$$

Linearised problem:

$$\partial_t f - 4\pi^2 ipk \cdot Xf + qi \left[P\left(k - \frac{X}{2}\right) - P\left(k + \frac{X}{2}\right) \right] \check{n}(X, t) = 0,$$

$$f(X, k, 0) = f_0(X, k) = \mathcal{F}_{x \rightarrow X}^{-1}[w_0], \quad \check{n}(X, t) = \int_{\mathbb{R}^d} f(X, \xi, t) d\xi.$$

Mild form:

$$f(X, k, t) - \overbrace{e^{4\pi^2 ipk \cdot Xt} f_0(X, k)}^{\text{free space solution}} =$$

$$= -qi \int_0^t e^{4\pi^2 ipk \cdot X(t-\tau)} \left[P\left(k - \frac{X}{2}\right) - P\left(k + \frac{X}{2}\right) \right] \check{n}(X, \tau) d\tau,$$

Integrate in k :

$$\check{n}(X, t) - \check{n}_f(X, t) = \int_0^t h(X, t - \tau) \check{n}(X, \tau) d\tau,$$

$$h(X, t) = 2q \sin(2\pi^2 pX^2 t) \check{P}(2\pi pXt),$$

Laplace transform:

$$\check{n}(X, \omega) = \check{n}_f(X, \omega) + \check{h}(X, \omega) \check{n}(X, \omega) \quad \Rightarrow$$

$$\Rightarrow \check{n}(X, \omega) = \frac{1}{1 - \check{h}(X, \omega)} \check{n}_f(X, \omega).$$

$$\tilde{n}(X, \omega) = \underbrace{\frac{1}{1 - \tilde{h}(X, \omega)}}_{\text{transfer function}} \tilde{n}_f(X, \omega), \quad \tilde{h} = \tilde{h}[P](X, \omega).$$

Penrose-type stability condition

$\exists \kappa > 0$ such that

$$\inf_{X, \operatorname{Re} \omega > 0} |1 - \tilde{h}(X, \omega)| \geq \kappa.$$

Then in principle we can invert $\tilde{n}(X, \omega) \mapsto \check{n}(X, t)$ and even get decay in time (with lots of technical work).

Theorem [A., Athanassoulis, Ptashnyk & Sapsis, KRM (2020)]

Let $P \in \mathcal{S}(\mathbb{R})$ be a background power spectrum of compact support which is **stable** in the sense that P satisfies the **Penrose stability condition**, and

$$\begin{aligned} \partial_t f - 4\pi^2 ipk \cdot Xf + qi \left[P\left(k - \frac{X}{2}\right) - P\left(k + \frac{X}{2}\right) \right] \check{n}(X, t) &= 0, \\ \check{n}(X, t) = \int_{\xi} f(X, \xi, t) d\xi, \quad f(X, k, 0) = f_0(X, k) \in \Sigma^r \end{aligned}$$

for $r \in \mathbb{N}$ large enough. Then $\exists C > 0$ s.t.

$$\|X\check{n}\|_{L^2_{X,t}} = \|\partial_x n\|_{L^2_{x,t}} \leq C \frac{\kappa + 1}{\kappa^2} \|f_0\|_{\Sigma^r} \quad (1)$$

and there exists a wave operator \mathbb{W} s.t.

$$\lim_{t \rightarrow +\infty} \|f(X, k, t) - E(t)\mathbb{W}f_0\| = 0. \quad (2)$$

- Contrary to usual LD for Vlasov, **no mean-zero required for $w_0(x, k)$** . Thus we have linear LD for energy-carrying wavetrains interacting with a homogeneous background.
- Explains why free-space dynamics works so well in so many cases.

Working with the (in)stability condition

How do you check

$$\exists \kappa > 0 \quad \inf_{X, \operatorname{Re} \omega > 0} |1 - \tilde{h}(X, \omega)| \geq \kappa?$$

More or less through

$$\exists X_* \quad \exists \operatorname{Re} \omega_* \geq 0 \quad \tilde{h}(X_*, \omega_*) = 1$$

A nonlinear system of two equations in three unknowns,

$$\operatorname{Re} \left(\tilde{h}(X_*, a_* + ib_*) \right) = 1 \quad \text{and} \quad \operatorname{Im} \left(\tilde{h}(X_*, a_* + ib_*) \right) = 0,$$

where of course $\omega_* = a_* + ib_*$.

Denote by $\mathbb{H}[f](t)$ the Hilbert transform,

$$\mathbb{H}[f](t) := p.v. \frac{1}{\pi} \int \frac{f(x)}{t-x} dx.$$

Theorem [A., Athanassoulis, Ptashnyk & Sapsis, KRM (2020)]

The following are equivalent:

$$(1). \quad \inf_{\substack{\operatorname{Re} \omega > 0, \\ X \in \mathbb{R}}} |1 - \tilde{h}(X, \omega)| = 0$$

$$(2). \quad \exists X_* \in \mathbb{R}, \quad \Omega_* \in \mathbb{C} \setminus \mathbb{R} \quad : \quad \mathbb{H}[D_{X_*} P](\Omega_*) = \mathbb{H}[D_{X_*} P](\bar{\Omega}_*) = \frac{4\pi p}{q}$$

or

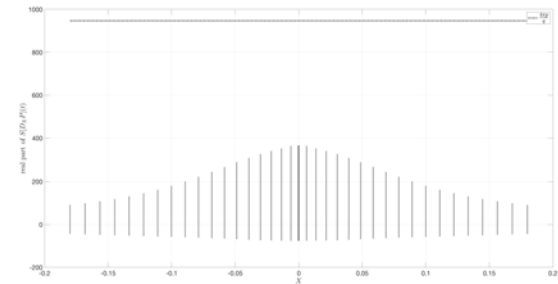
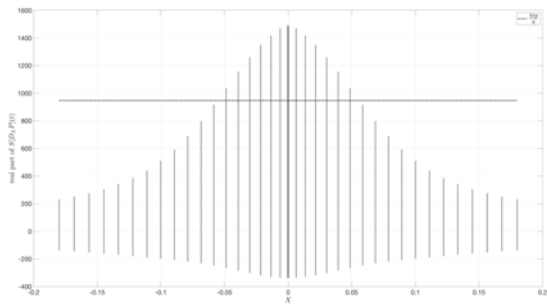
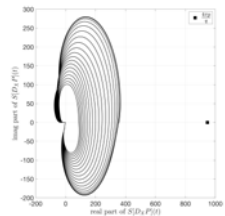
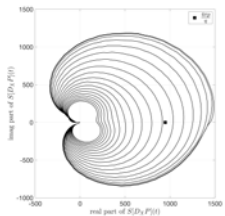
$$\exists X_*, \Omega_* \in \mathbb{R} \quad : \quad \mathbb{H}[D_{X_*} P](\Omega_*) = \frac{4\pi p}{q} \quad \text{and} \quad D_{X_*} P(\Omega_*) = 0.$$

$$(3). \quad d(\bar{\Gamma}, 4\pi p/q) = 0, \quad \text{where} \quad \mathbb{S}[f](t) = \mathbb{H}[f](t) - if(t) \quad \text{and}$$

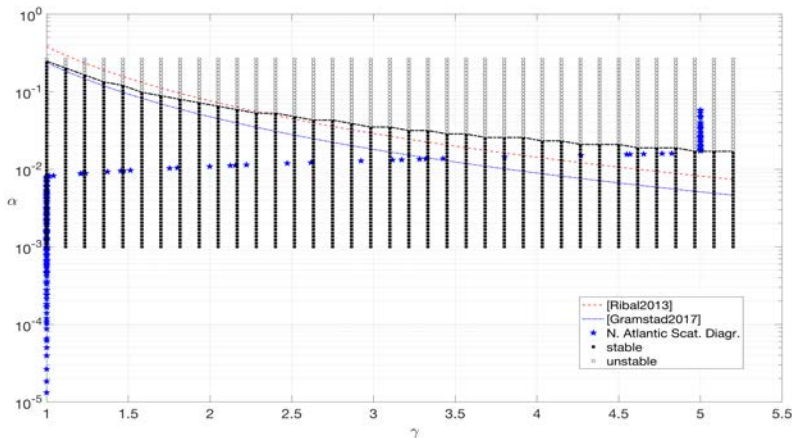
$$\Gamma_X := \{\mathbb{S}[D_X P(\cdot)](t), \quad t \in \mathbb{R}\} \cup \{0\}, \quad \overset{\circ}{\Gamma}_X = \{z \in \mathbb{C} \mid z \text{ enclosed by } \Gamma_X\},$$

$$\bar{\Gamma} := \overline{\bigcup_{X \in \mathbb{R}} \overset{\circ}{\Gamma}_X}.$$

The stability condition



Stability region for JONSWAP [AAPS KRM 2020]

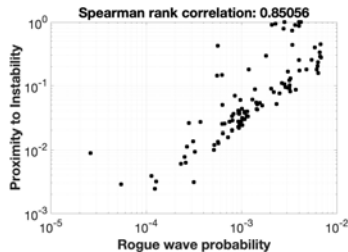
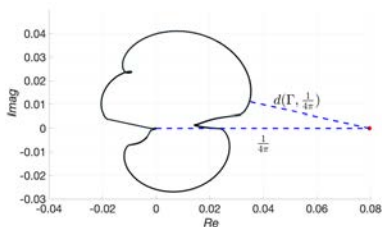


North Atlantic Scatter Diagram data from [DNV-GL, DNVGL-RP-C205: Environmental Conditions and Environmental Loads, Tech. Rep., August 2017]

Alber v. HOSM+Monte Carlo, [A., Gramstad, Fluids 2021]

Are there “more stable” and “less stable” spectra?

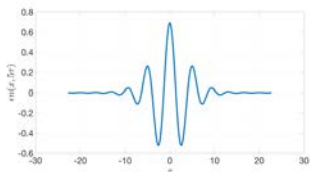
Nondimensional “**proximity to instability**” according to our analysis
versus
Monte Carlo simulations of the same sea state with a broadband solver.



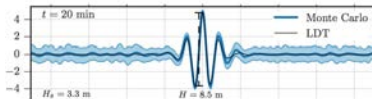
If there are unstable wavenumbers,

$$\tilde{h}(X_*, \omega_*) = 1 \quad \text{for some } X_0 \in \mathbb{R}, \operatorname{Re} \omega_* > 0$$

they give rise to **unstable modes**. These seem to successfully capture some inherent scalings for Rogue waves.



[A., Athanassoulis, Sapsis, JOEME (2017)]
Scalings of unstable modes



[Dematteis, Grafke, Vanden-Eijden, PNAS (2018)]
Monte Carlo + Large Deviations Theory
for fully Nonlinear simulations of mNLS

Summary

- Alber equation: 2^{nd} moment theory for NLS with stochastic initial data over a homogeneous background
- **Key features:**
bifurcation between dispersion & modulation instability
mathematical theory analogous to LD, many open questions still
- **Why ocean engineers care:**
Finally takes into account metocean data!
Results are plausible when compared to ocean data
Provides insights on development of extreme events
- 2D, broadband versions of this are possible

Thank you very much!